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12-23-02
P12

PATENT
81842.0014

Express Mail Label No.: EL715817449US

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re application of:

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Serial No: 09/800,896

Filed: March 8, 2001

For: LINK WRITING METHOD FOR A
RECORDABLE COMPACT DISK AND
DRIVER FOR USING THE METHOD

Art Unit: Not Assigned

Examiner: Not Assigned

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SUBMISSION OF SUBSTITUTE SPECIFICATION

Commissioner for Patents
Washington, D.C. 20231

Dear Sir:

The applicant submits a substitute specification to correct translation errors, typographical errors and non-idiomatic language. Enclosed is a marked up copy showing deleted text with strikeout markings and added text with underlines. Also enclosed is a clean copy of the specification. No new matter is added.

Applicant appreciates that there is no requirement to discuss the amendments to the specification when submitting a substitute specification. For the convenience of the Examiner and for clarity, the applicant will nevertheless comment on certain of the amendments made in this substitute specification.

The title is altered to make its description more accurate. Both recordable and re-writable optical disk media are discussed in the application, with the strategies of the invention applied to both types of media. The reference to a driver is corrected to be a reference to a drive, correcting a typographical or translation error that is apparent due to the illustration in the application's drawings of a drive in FIG. 4 and the corresponding reference in the original text to that figure as showing a driver.

12/10/2002 NMOHAMH1 00000009 09800896

01 FC:2202
02 FC:2201

144.00 OP
126.00 OP

The field of the invention is altered to clarify that the described technology finds applications in both recordable and re-writable disks, consistent with the examples provided in the specification. Similar changes are made elsewhere in the specification to clarify the applicability of the invention.

Applicant adds a paragraph to the summary of the invention. This is a paraphrasing of one of the original independent claims.

Certain of the implementations of the described invention were originally referenced by the term "blank area identifying method." Applicant has changed this term in its general usage to the term "pattern identifying method," because the implementations referenced in the specification included identifying both blank (or unwritten) areas and areas that were written with a constant value. As such, the original term was somewhat inconsistent and this inconsistency is addressed by the amendment.


Amendments are also offered to the claims. Claim 1 is broadened in the preamble to clarify that its method relates to writing links on recordable or rewritable optical disks. Other amendments are made to address grammar and translation errors in the claims; these amendments are not intended to narrow the claim. The final clause of claim 1 is broadened to clarify that the method need not precisely match the ending point of the interrupted data with the starting point of the restarted data writing. This corresponds, for example, to the discussion in paragraph 61 of the original published application in which the interrupted and restarted writing processes overlap. This also corresponds to the method described in paragraph 68 of the original published application, where a blank area (that is, a gap) is created between the interrupted data and the restarted data writing. Similar amendments are made to claim 7.

For claims 2-6, 8-11, 13-14 and 16, amendments are made to address grammar and translation errors, and also to correct inaccurate descriptions of disk structures; these amendments are not intended to narrow these claims.

Applicant requests that the enclosed substitute specification be entered and the application examined.

Respectfully submitted,

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LINK WRITING METHOD FOR A RECORDABLE OR REWRITABLE COMPACT
DISK AND ~~DRIVER-DRIVE~~ FOR USING THE METHOD

BACKGROUND OF THE INVENTION

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1. Field of the Invention

[0001] This invention relates to a writing method and device for a recordable or rewritable compact disk (~~CD-R~~), and more particularly, to a link writing method and device ~~with the function for succeeding~~ that restarts writing after writing the has been interrupted ~~recording~~ CD-R.

2. Discussion of the Related Art

[0002] ~~Optical~~ Recordable or rewritable optical disk media typically include a continuous spiral groove which extends for the entire data storage capacity of the disk. CD-based (~~CD-R or DVD-R~~) optical disk media ~~architecture architectures~~ utilizes-utilize a the continuous spiral groove with sectors (also called "~~block~~blocks") of equal length, which are accessed at a constant linear velocity (CLV).

[0003] A recordable compact disk (CD-Recordable or CD-R) or a rewritable compact disk (CD-Rewritable or CD-RW) is a CD-based optical disk medium, and includes a continuous spiral CLV groove. Input data are modulated and ~~wrote~~ written into the continuous spiral CLV groove. In general, the coding modulation of

stored CD-R data is an ~~8-14~~eight-to-fourteen modulation (EFM, ~~eight-to-fourteen~~
~~modulation~~). The so-called EFM is ~~to~~eight-to-fourteen modulation turns the input
data signal, along with error correction data, address information, ~~Syne~~sync
pattern (synchronization pattern), and other miscellaneous content, into an encoded
binary stream of bits, expanding every eight bits of ~~input~~ data into fourteen bit
words, with an additional three bits inserted into the bit stream to separate words.

[0004] FIG. 1 shows the data specification for each recording sector in a CD-
based optical disk medium. As shown in FIG. 1, each recording second includes 75
recording blocks and each ~~of~~ recording ~~blocks~~ block includes 98 data frames.
Moreover, each of the data frames ~~includes~~consists of 588 channel bits ~~which are~~
~~constituted by~~ including a ~~Syne~~sync pattern containing 24 channel bits, control and
display data containing 14 channel bits, information data, ~~and the~~ correction parity
data and other information etc. Since the CD-R data storage scheme does not
provide ~~the~~ identification marks along the groove to identify data recording
positions precisely, each recording sector ~~are therefore~~is formatted with a ~~headers~~
header having a great deal of information to aid in synchronizing the rotation of the
disk and obtaining data framing, ~~including~~. The sector header adds a great deal of
overhead to the sector. Moreover, a limited number of entries may be placed in the
table of contents (TOC) on the CD-R disk for locating the beginning of the recorded
areas. Therefore, it is very important for a CD-R storage device not to interrupt the
data writing process because of the overhead penalty.

[0005] Current CD-R storage devices ~~therefore have~~ use a buffer ~~to that~~ accumulate ~~accumulates~~ the input data ~~to and~~ organize ~~organizes~~ the data into sectors for writing on the disk in a continuous sequence of sectors. When the ~~current~~ buffer of a current CD-R storage device ~~fails to~~ does not receive input data from the host on a timely basis (due to higher priority tasks or interrupts using host resources), the buffer may under-run and ~~will~~ may become empty, causing the writing process to be halted ~~in an orderly fashion~~. This ~~will~~ results in a data file being partially written. One proposed solution, which is undesirable, is to stop writing sectors upon the occurrence of the under-run. It is not possible to restart the writing process after stopping because ~~due to that~~ the succeeding recording position ~~can not~~ cannot be located precisely. Most often, the user application cannot deal with the problem of linking ~~problem~~ between a prior recording process and a succeeding recording process, so the disk is considered ruined and is discarded.

[0006] In ~~the~~ light of this problem, ~~the~~ U.S. Pat. No. 6,119,201 ~~disclosed~~ discloses a method ~~of~~ employing a formatted padding sector to resolve the under-run problem. The method disclosed by the patent ~~is to write~~ writes one or several formatted padding sectors ~~for substituting and replenishing the~~ when a buffer encounters an under-run condition. While the method can resolve the under-run problem without stopping writing, it wastes ~~the disk's sector~~ disk space as it requires ~~to replenish~~ writing one or ~~a multiple of~~ several complete formatted padding ~~sector~~ sectors. Moreover, the method wastes time in reading since it needs to judge if the read data ~~need to replenish~~ are padding sectors or not. What is more, the

method ~~can not~~cannot overcome the problem of writing interruption caused by ~~the~~a servo problem.

[0007] Therefore, it is necessary to have a link writing method and device for a recordable compact disk to ~~directly succeed~~restart the writing process at the ~~address~~location where it is interrupted. This ~~is to~~would effectively resolve the problems of writing interruption caused by ~~the~~buffer under-run or other problems.

[0008] FIG. 2 ~~is~~illustrates the situation ~~that in which~~ the data frame of the succeeding (restarted) writing process overlaps the previous data frame according to a prior ~~art~~strategy. As the demand on the length of the data frame ~~of~~stored on the CD-based medium is rigorous, the length of the data frame ~~has to~~is set ~~as to~~588T (bits) in order to correctly read the data written. But as shown in FIG. 2, if the (n+1)th data frame ~~that is~~ written before the interruption ~~is overlapped by~~and the (n+2)th data frame ~~causing is~~ written imprecisely after the interruption, the later written frame may overlap the previously written frame. The resulting overlap may cause a reading drive to be unable ~~the inability~~ to differentiate between the two written data frames, and a data reading error of the data will occurs. As shown in FIG. 2, either range (A) is treated as two frames or range (B) is treated as one frame and either will cause a data reading error.

[0009] Moreover, FIG. 3 ~~is~~illustrates the situation that the data frame of the succeeding writing forms a gap with the previous data frame according to a prior ~~art~~strategy. As shown in FIG. 3, ~~whenever a linking gap appears~~may appear between ~~the~~a written nth frame and a succeeding written (n+1)th frame when the

writing is interrupted between the n^{th} and $(n+1)^{\text{th}}$ frames. In this situation a ~~and~~
~~the written n^{th} frame when interrupted,~~ reading error also occurs. This is because
~~that the linking gap has redundant channel bits, thereby, causing the inability~~
~~of which cause the access driver reading drive to be unable to differentiate between~~
the data frames when it is reading. For instance, as shown in FIG. 3, either range
(A) is treated as two frames or range (B) is treated as one frame and either will
cause a data acquisition error. Therefore, it is very important to position the writing
interruption address accurately and to ~~succeed~~ begin successive writing accurately.

SUMMARY OF THE ~~INVENTION~~ PREFERRED EMBODIMENTS

[0010] It is therefore an objective of the invention to provide a link writing
method for a recordable or rewritable compact optical disk (CD-R) and a driver
drive for using the method for resolving the problem of writing interruption ~~resulted~~
resulting from a data under-run or other causes ~~cause~~ during the writing process of
the ~~recordable compact optical~~ disk.

[0011] ~~According to an~~ An aspect of the invention, ~~there is provided~~ provides a
link writing method for a recordable or rewritable optical compact disk (CD-R),
comprising ~~the steps of:~~ recording a an interrupted position by storing values of an
interrupted sector, an interrupted data frame, and an interrupted bit count when
data under-run or other causes occur ~~in the driver, and enabling~~. The method
enables a succeeding writing process when the ~~causes causing~~ cause for the writing
interruption is eliminated. The ~~step of succeeding writing process comprising~~

comprises positioning a linking area in accordance with the values of the interrupted sector, the interrupted data frame, and the interrupted bit count; The method includes enabling the start writing signal; and settling the laser power. The linking area ~~comprises the steps of~~ process includes:

[0012] (1) reading the values of the interrupted sector, the interrupted data frame, and the interrupted bit count of the interrupted position;

[0013] (2) setting the linking position, including starting sector, starting frame and starting bit count;

[0014] (3) searching the interrupted sector area by counting the sector's SYNC signal to the starting sector;

[0015] (4) searching the interrupted data frame area by counting the EMFM's SYNC signal to the starting frame; and

[0016] (5) searching the interrupted bit area by counting the EFMCLK's pulse signal to the starting bit count.

[0017] Therefore, the linking area is linked to the interrupted position accurately and the length of the data frame is ~~kept constant~~ written without causing uncorrectable errors on during data reading.

[0018] Another aspect of the invention provides a link writing method for a recordable or rewritable optical disk including recording an interrupted position by storing values of an interrupted sector, an interrupted data frame, and an interrupted bit count when data under-run or other interruption occurs. The method enables a succeeding writing process after the writing interruption. The

succeeding writing process comprises searching a linking area by comparing a read data length with a maximum run-length value, enabling a start writing signal, and activating a laser power, wherein the linking area is linked to the interrupted position sufficiently accurately that the interrupted data and successively written data together form interrupted and successively written data that can be successfully error-correction processed.

BRIEF DESCRIPTION OF THE DRAWINGS

[0019] The objectives, characteristics, and advantages of the present invention can be more fully understood by reading the following detailed description of the preferred ~~embodiment~~embodiments, with reference made to the accompanying drawings as follows:-

[0020] FIG. 1 shows the data specification for each recording sector according to ~~a~~the prior art.

[0021] FIG. 2 ~~is~~illustrates the situation that ~~the~~a successively written data frame ~~of the succeeding writing overlaps the previous~~previously written data frame according to a prior art strategy.

[0022] FIG. 3 ~~is~~illustrates the situation ~~that therein~~in which a successively written data frame ~~of the succeeding writing forms a gap with the previous data~~ frame according to a prior art strategy.

[0023] FIG. 4 is a block diagram of the recordable ~~compact optical~~compact optical disk ~~driver~~drive of the invention.

[0024] FIG. 5 is a flow chart for detecting the linking area of an embodiment of the invention.

[0025] FIG. 6 is a flow chart for detecting the linking area of another embodiment of the invention.

[0026] FIG. 7 ~~is illustrates~~ the correct linking situation between the data frame of ~~the~~ a succeeding writing process and ~~the~~ a previously written data frame making use of the embodiments in FIG. 5 and FIG. 6 according to the invention.

[0027] FIG. 8 is a flow chart for detecting the linking area of ~~one~~ another embodiment of the invention.

[0028] FIG. 9 ~~is illustrates~~ the correct linking situation between the data frame of ~~the~~ a succeeding writing process and ~~the~~ a previously written data frame making use of the embodiment in FIG. 8 according to the invention.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENT EMBODIMENTS

[0029] The link ~~driving~~ writing method of a recordable or rewritable compact disk drive having a succeeding writing function of ~~the invention~~ firstly employs an encoding link controller to precisely position the linking area; and then enables a writing start signal in order to commence a succeeding writing process. ~~Following is the description of the invention accompanied by the drawings.~~

[0030] FIG. 4 is a block diagram of the recordable compact disk ~~driver~~ drive having a succeeding writing function according to the present invention. As shown in FIG. 4, the recordable or rewritable compact disk ~~driver~~ drive 10 includes a host interface 12, a memory controller 14, a CD-ROM decoder 16, a CIRC decoder 18,

and a sub-code decoder 20. It also includes an eight-to-fourteen (EFM) demodulator 22, a SYNC pattern detector 24, a data slicer 26, a servo controller 28, an ATIP decoder 30, an encode link controller 32, a CD-ROM encoder 34, a CIRC encoder 36, a sub-code encoder 38, an EMFM modulator 40, a writing circuit 42, and a micro controller 44. The functions of most of the units shown in FIG. 4 are the same as those of the conventional recordable compact disk ~~driving device of the prior art drive~~. The only difference is that the encoding link controller 32 included in the ~~invention~~ illustrated embodiment can be used to precisely position the predetermined writing address (linking area) according to the position information signals generated from the SYNC pattern detector 24, sub-code decoder 20 and ATIP decoder 30. When the encoding link controller 32 detects the linking area, it generates a "start writing signal" to the micro-controller 44 so as to perform the action of succeeding writing. The function of the sub-code decoder 20 is to detect and output the time position information of the recorded block, while the function of the ATIP decoder 30 is to detect and output the ATIP time code (MSF information, Minute, Second, Frame) beforehand recorded ~~or on~~ blank discs.

[0031] Two detecting methods are provided to precisely detect the linking area according to the present invention. The first one is the "data decoding method" ~~while and~~ the other one is the "~~blank area~~pattern identifying method". The "data decoding method" makes use of a decoding circuit to count the block, the frame, and the channel bits of the previously recording-recorded and interrupted data block ending position to precisely detect the interrupted position as the linking area. The

decoding circuit ~~can firstly search~~first searches the ATIP identifying data (MSF information) of the linking area and then precisely ~~detect~~detects the linking area by counting the channel bits. The "~~blank area~~pattern identifying method" is ~~to detect~~detects a characteristic pattern such as a long ~~-high-reflectivity or long low-reflectivity~~ the non-recording or blank location as the linking area.

[0032] Generally speaking, whenever the write error of the recordable compact disk ~~driver-drive~~ occurs such as an under-run or servo error, the driver will enable the write error signal and stop the write action. The ~~driver-drive~~ of the invention, in the mean time, also stores the write interruption address into registers. The data of the write interruption address ~~include~~includes the current time code of the block (also called MSF, Minute, ~~and~~ Second, Frame), current counted value of the EFM frame, and current counted value of EFM channel bit. These data are stored into the MSF register, the EFM⁻SYNC⁻CNT register, and the EFM⁻BIT⁻CNT register, respectively. The encoding link controller 32 can thereby use the write interruption address as the start address index when it comes to succeeding writing in order to precisely locate the linking area.

[0033] Three stages are used to precisely detect the linking area by the encoding link controller 32. The first stage is the MSF counting, the second stage is the frame counting, and the third stage is the channel bit counting. The ~~driver-drive~~ 10, after reading sufficient data or overcoming the interruption problem, will enable the succeeding writing process and start the encoding link controller 32, and in the same time, read the written area on the disk sequentially. Then, encoding link

controller 32 will precisely position the linking area in accordance with the position information signals generated by the SYNC pattern detector 24 and the sub-code detector 20. Thereafter, the encoding link controller 32 sends the start writing signal to the ~~micro-controller~~microcontroller 44 to perform the action of succeeding writing. FIG. 5 is a flow-chart illustrating an embodiment ~~of flow-chart~~ for detecting the linking area. ~~In referring~~Referring to FIG. 5, the action of the encoding link controller 32 is ~~described~~illustrated as follows:

[0034] Step S500: Start the succeeding ~~Write~~write.

[0035] Step S502: Read the data from MSF, EFM⁻SYNC⁻CNT, and EFM⁻BIT⁻CNT registers. Use ~~and the positional data are used as the starting~~ address of the linking area.

[0036] Step S504: Perform the first stage counting and start the MSF counter.

[0037] Step S506: Count the output signal generated from the sub-code decoder 20 ~~by using~~ the MSF counter.

[0038] Step S508: Compare if the counted value of the MSF counter ~~has already equalled to~~equals the value in the MSF register. If it ~~has is equal~~, ~~jumps~~ jump to step S510, otherwise, ~~jumps~~jump back to step S506.

[0039] Step S510: Perform the second stage counting and start the frame counter.

[0040] Step S512: Count the output signal generated from the SYNC pattern detector 24 ~~by using~~ the frame counter.

[0041] Step S514: Compare if the counted value of the frame counter ~~has already equalled to~~equals the value in the EFM⁻ SYNC⁻ CNT register. If it ~~has~~is equal, ~~jumps-jump~~ to step S516, otherwise, ~~jumps-jump~~ back to step S512.

[0042] Step S516: Perform the third stage counting and start the Bit-bit counter.

[0043] Step S518: Count the pulse signal of the EFMCLK ~~by using~~ the bit counter.

[0044] Step S520: Compare if the counted value of the bit counter ~~has already equalled to~~equals the value in the EFM⁻ BIT⁻ CNT register. If it ~~has~~is equal, ~~jumps~~jump to step S522, otherwise, ~~jumps-jump~~ back to step S518.

[0045] Step S522: Enable a WRITE_START signal and activate the writing laser power.

[0046] Moreover, the steps shown in FIG. 5 make use of the sub-code decoder 20 to detect the written block time code and position the linking area ~~that is in~~relation to the interrupted writing process. Besides using this method, ~~the invention~~this discussion also presents a method making use of ATIP decoder 30 to detect the ATIP time code, which is pressed on a disk in advance, and to locate the linking ~~block that is~~area after the interrupted writing process.

[0047] By the use of this method for locating the linking area, the ~~driver-drive~~ will store the address of the writing interruption area into registers. The process for storing data includes storing the counted value of the current block into the MSF register, and storing the block's written bit into the BIT⁻ CNT register. Afterward,

the encoding link controller 32 can make use of the value of the registers as the index of a starting address to locate precisely the linking area for a succeeding writing process.

[0048] Two stages are used to precisely locate the linking area by the encoding link controller 32. The first stage is the MSF counting, and the second stage is the channel bit counting. The ~~driver-drive~~ 10, after reading sufficient data or overcoming the interruption problem, will enable the succeeding writing process and start the encoding link controller 32. Then, encoding link controller 32 will precisely position the linking area in accordance with the output signals of the ATIP detector 30 and the EFMCLK pulse. Thereafter, the start writing signal is transmitted to the ~~micro-controller~~microcontroller 44 to perform the action of succeeding writing.

[0049] FIG. 6 is ~~an another embodiment of a~~ flow chart illustrating another embodiment for detecting the linking area of the invention. ~~In referring~~Referring to FIG. 6; the action of the encoding link controller 32 is ~~described~~illustrated as follows:

[0050] Step S600: Start the succeeding ~~Write~~write.

[0051] Step S602: Read the data from MSF and BIT⁻CNT registers and use the data ~~are used as~~ the positional data for detecting the linking area.

[0052] Step S604: Perform the first stage counting and start the ATIP search.

[0053] Step S606: Make use of the ATIP decoder 30 to search each of the MSF time ~~code~~codes of the ATIP sequentially.

[0054] Step S608: Compare if the value of the ATIP time code ~~has already~~
~~equalled to~~equals the value in the MSF register. If it ~~has~~is equal, ~~jumps-jump~~ to step
S610, otherwise, ~~jumps-jump~~ back to step S606.

[0055] Step S610: Perform the second stage counting and start the bit counter.

[0056] Step S612: Count the EFMCLK pulse signal ~~by~~using the bit counter.

[0057] Step S614: Compare if the counted value of the bit counter ~~has already~~
~~equalled to~~equals the value in the BIT⁻CNT register. If it ~~has~~is equal, ~~jumps-jump~~ to
step S616, otherwise, ~~jumps-jump~~ back to step S612.

[0058] Step S616: Enable a WRITE_START signal and activate the writing
laser power.

[0059] Therefore, after the linking area is located by one or another of the
above-mentioned methods, the encoding link controller 32 activates the writing
laser immediately and enables the WRITE_START signal. Moreover, the succeeding
writing action is started as soon as the ~~micro-controller~~microcontroller 40 of the
~~driver-drive~~ 10 receives the "WRITE_START" signal. As the encoding link controller
32 includes three stages of counting, the accuracy of the linking position can be
controlled within one bit. Therefore, the starting address of the succeeding writing
will not ~~be overlapped~~overlap with the written data ~~interrupted~~preceding the
interruption, nor will ~~it be formed at the~~ the succeeding writing have a gap with the
written data.

[0060] FIG. 7 ~~is~~illustrates the correct writing situation between the data
frame of the succeeding writing and the ~~previous~~previously written data frame

obtained by making use of the embodiments illustrated in FIG. 5 and FIG. 6.

Assume that up to the n^{th} data frame is written and then stopped by the ~~driver~~ drive 10 because of ~~the~~ a buffer under-run. Afterward, when the ~~driver~~ drive 10 ~~read~~ reads sufficient data from the host such that the writing action can be continued, the ~~driver~~ drive 10 enables the encoding link controller 32. In this way, the ~~driver~~ drive 10 can perform the writing action immediately and ~~writing~~ write the $(n+1)^{\text{th}}$ data frame and ~~the subsequent data frame~~ frames when the ~~optic~~ optical head is ~~driven to~~ located at the linking area. ~~So the driver~~ The drive 10 can finish the recording (writing) procedure as if no interruption occurrence occurred, and ~~no~~ without any data miss between the two successive recordings. Again, as shown in FIG. 7, the succeeding writing of the $(n+1)^{\text{th}}$ data frame will not overlap with the n^{th} data frame written by the previous interrupted recording. Moreover, the succeeding $(n+1)^{\text{th}}$ data frame will also not form a blank gap ~~either~~ with the n^{th} data frame. Consequently, the length of the data frame can be controlled within 588T without causing data acquisition error.

[0061] ~~Due to the~~ The data recorded on the disc ~~is~~ will be incomplete during the write laser power settling stage, ~~this~~ which will cause data ~~grabbing~~ error ~~reading errors~~. If the succeeding recording start position is the same as the stop position of a previous recording ~~procedure~~ process, the ~~range~~ extent of erroneous data is the write laser power settling time. If the write laser power settling time can be determined, the ~~driver~~ drive 10 can advance the succeeding recording start position according to the settling time. Then the previous recording

data and succeeding recording data will overlap at the initial position of the succeeding writing process. Because the laser power is not enough (during the settling time) to write in the overlap area, the data at recorded in the overlap area will not be destroyed. If the write laser power settling time can be estimated accurately, then the error data number can be ~~downed~~ reduced to "0" ideally in the ideal case. If the write laser power settling time is estimated in error, a common driver can correct the partially erroneous bit data by using the CIRC decoding process. As a result, although a portion of the bit data in the invention is unstable before the laser light source is stabilized, this unstable bit data will not cause erroneous reading of the data since the unstable bit data can be corrected by the CIRC decoding process.

[0062] Following is the explanation of the principle of the "~~blank area~~ pattern identifying method" of the invention. Since a common storing medium of the "write-once disk" has relatively high reflectivity, the reflected "radio frequency" (RF) signal maintains ~~on~~ constant at a relatively high level of reflectivity for an unwritten area on the disk. And since the maximum run-length (MRL) of the EFM data is limited to a constant range, e.g. 11T for CD format, the data length following an interruption will be greater than the MRL value when the data of the blank area (unwritten area) are acquired by the ~~driver~~ drive. Therefore, the blank area can be detected by judging whether or not the data acquired is greater than the maximum run-length. The "~~blank area~~ pattern identifying method" of the invention is employed to detect, for example, the blank area that is used as the linking area of

the succeeding writing. FIG. 8 is a flow chart illustrating a method for detecting the linking area of ~~one other another~~ embodiment of the invention. ~~As referring to FIG. 8, the illustration of~~ illustrates the blank area embodiment of the "blank areapattern identifying method" of the invention is as follows:

[0063] Step S800: Start the succeeding Writewrite.

[0064] Step S802: Set MRL.

[0065] Step S804: Read the register data EFM⁻BIT⁻CNT and add the MRL to the register data to assure the correct length of the data frame.

[0066] Step S806: Judge if the data acquired is greater than the MRL. If it is ~~se greater,~~ jumps-jump to step S808, otherwise, continue the step.

[0067] Step S808: Enable a WRITE_START signal and settle a writing laser power.

[0068] While making use of the blank area embodiment of the "blank areapattern identifying method" in detecting the blank area, ~~since the detected area has exceeded~~ will exceed the MRL's bit number value, so Step 804 is employed to add the MRL to the EFM⁻BIT⁻CNT register data as recording preset length to assure the correct length of the data frame. FIG. 9 ~~is~~ illustrates the correct linking situation between the data frame of the succeeding writing and the previous recording data frame. As shown in FIG. 9, although the method also generates a portion of blank data (the MRL plus the laser power settling time), since the ~~bit~~ number of bits in the linking frame still ~~remains~~ corresponds to the correct length, such as 588T, the blank area can still be corrected by the CIRC decoding process.

[0069] Furthermore, as far as the write-once disc is concerned, since all the blank area belongs to an area with relatively high reflectivity, the blank area after the writing interruption can be detected accurately by employing the "blank area embodiment of the "pattern identifying method". NeverthelessOn the other hand, as far asfor the Re-Writable disk is concerned, since the data can be over-written directly in the data area, and so the linking area after the writing interruption ~~can~~ not~~cannot~~ be identified by directly employing the "blank area embodiment of the "pattern identifying method". In order to be able to identify the linking area for the Re-Writable disk after writing interruption by the use of the "blank area "pattern identifying method", a section of pattern data has to be written after the writing interruption. And the section of pattern data must have the same reflectivity and have a data length greater than the MRL. In this way, the pattern data can then be employed by the "blank areapattern identifying method" to identify the linking area after the writing interruption.

[0070] To summarize the foregoing ~~statement~~, the link writing method for a recordable or rewritable compact disk and the ~~driver for~~drive using the method of the invention makes use of the encoding link controller to precisely detect the linking area, and starts the succeeding writing process. Therefore, it can continue to finish the writing action to assure that ~~the length of each~~ a readable data frame is ~~constant~~ can be written when data under-run or some other servo problems occur. ~~Due to~~Because the data frame length ~~keep is constant~~ near nominal, such as 588T, ~~during~~ including the linking area, this can be treated as a non-interrupted

recording area and will not appear to be a decoding error during a subsequent reading cycle. Moreover, since the link writing method for a recordable or rewritable compact disk and the ~~driver~~ drive for using the method of the invention directly connects the data stored on the disk after being interrupted, it is treated as a normal recording procedure ~~and now~~ without any retrieval needed.

[0071] The invention has been described ~~using in terms of an~~ exemplary preferred ~~embodiment~~ embodiments. However, it is to be understood that the scope of the invention is not limited to the disclosed ~~embodiment~~ embodiments. On the contrary, it is intended to cover various modifications and similar arrangements. The scope of the claims, therefore, should be accorded the broadest interpretation so as to encompass all such modifications and similar arrangements.

What is claimed is:

1. A link writing method for a recordable or rewritable compact optical disk (~~CD-R~~) comprising the steps of:

recording ~~a~~ an interrupted position by storing values of an interrupted sector, an interrupted data frame, and an interrupted bit count when data under-run or other ~~causes occur~~ interruption occurs in the driver; and enabling a succeeding writing process ~~when the causes causing~~ after the writing interruption is eliminated, the succeeding writing process comprising:

positioning a linking area in accordance with the values of the interrupted sector, the interrupted data frame, and the interrupted bit count;

enabling ~~the~~ a start writing signal; and

activating ~~the~~ a laser power;

——wherein the linking area is linked to the interrupted position but is allowed to precede or be spaced from the interrupted position accurately and the length of so that the interrupted data frame is kept constant without causing errors on data reading together with successively written data can be successfully error-correction processed.

2. The ~~link writing method according to~~ of claim 1, wherein the step of positioning the linking area comprises the steps of:

reading the values of the interrupted sector, the interrupted data frame, and the interrupted bit count of the interrupted position;

setting ~~the~~ a linking position, including starting sector, starting data frame and starting bit count;

searching the interrupted sector area by counting ~~the sector's~~ a sector SYNC signal to the starting sector;

searching the interrupted data frame area by counting ~~the EFM's~~ an EFM SYNC signal to the starting frame; and

searching the interrupted bit area count by counting ~~the EFMCLK's~~ an EFMCLK pulse signal to the starting bit count.

3. The ~~link writing method according to~~ claim 2, wherein the starting sector, ~~is set as,~~ the starting data frame, and the starting bit count are set according to the interrupted sector, ~~the starting data frame is set as the interrupted data frame, and the starting bit count is set as the interrupted bit count.~~

4. The ~~link writing method according to~~ claim 3, wherein ~~the corresponding~~ an area length of corresponding to a laser power settling time is subtracted from both the interrupted position and the linking position.

5. The ~~link writing method according to~~ claim 1, wherein the ~~step of~~ positioning the linking area comprises ~~the steps of:~~

reading the values of the interrupted sector, the interrupted data frame, and the interrupted bit count of the interrupted position;

setting ~~the~~ a linking position, including starting sector and starting bit count;
searching the interrupted sector ~~area~~ by comparing ~~the~~ an ATIP time code
with the starting sector; and
searching the interrupted bit ~~area~~ count by counting ~~the~~ EFMCLK's an
EFMCLK pulse signal to the starting bit count.

6. The ~~link writing method according to~~ claim 5, wherein ~~the~~ a value of the
starting bit count is ~~the~~ set to be a written bit count of the interrupted sector.

7. A link writing method for a recordable or rewritable ~~compact optical~~ disk
(~~CD-R~~) comprising the steps of:

recording ~~a~~ an interrupted position by storing values of an interrupted sector,
an interrupted data frame, and an interrupted bit count when data under-run or
other ~~causes occur in the driver~~ interruption occurs; and

enabling a succeeding writing process ~~and setting the judged maximum run-~~
~~length value when the causes causing after~~ the writing interruption is eliminated,
the succeeding writing process comprising:

searching ~~the~~ a linking area by comparing ~~the~~ a read data ~~width~~ length with
a maximum run-length value;

enabling ~~the~~ a start writing signal; and

activating ~~the~~ a laser power;

——wherein the linking area is linked to the interrupted position ~~accurately and~~
~~the so that length of the interrupted data frame is kept constant without causing~~
~~errors on data reading together with successively written data can be successfully~~
error-correction processed.

8. The ~~link writing method according to~~ claim 7, wherein the ~~step of searching~~
the linking area comprises ~~the steps of:~~

reading ~~the values of the interrupted block~~sector, the interrupted data frame,
and the interrupted bit count of the interrupted area;

setting ~~the values of a starting block, a starting data frame, a starting bit~~
count of ~~the a~~ writing starting area, and the ~~judged~~ maximum run-length value;
and

detecting ~~the area where the~~ read data length is greater than the maximum
run-length ~~in order to be used as~~ value and setting the linking area in response
thereto.

9. The ~~link writing method according to~~ claim 8, wherein the writing starting
area is set according to the interrupted area position plus and the maximum run-
length value so as to maintain the data frame with ~~the a~~ same length.

10. The ~~link writing method according to~~ claim 8, further comprising ~~a step of~~
writing a section of low ~~reflective~~ reflectivity pattern data following the interrupted

~~area when the recordable compact disk is a Re-writable compact disk position,~~
wherein ~~the~~ a length of the low ~~reflective-reflectivity~~ pattern data is greater than
the maximum run-length value ~~of the Re-writable compact disk~~ value.

11. The ~~link writing method according to~~ claim 8, further comprising a step of
writing a section of high ~~reflective-reflectivity~~ pattern data following the
~~interrupted area when the recordable compact disk is a Re-writable compact~~
~~disk position,~~ wherein ~~the~~ a length of the high ~~reflective-reflectivity~~ pattern data is
greater than the maximum run-length value ~~of the Re-writable compact disk~~.

12. ~~A recordable compact~~ An optical disk driver drive having the function of a link
writing function, comprising:

a sub-code decoder for providing block SYNC signal and reproduced time code
information while reading ~~the data of the~~ from a disk;

a SYNC pattern decoder for providing EFM SYNC signal while reading ~~the~~
~~data off~~ from the disk;

an encoding link controller for positioning a link area and ~~starting~~ generating
a succeeding writing signal; and

a ~~micro-controller~~ microcontroller for receiving the succeeding writing signal
of the encoding link controller and starting a succeeding writing process; and

a laser responsive to the succeeding writing signal, the laser powered in a
succeeding writing process to provide laser power to an optical disk at a position

corresponding to data written prior to a data writing interruption, thereby exposing previously written data.

13. ~~The recordable compact disk driver according to~~drive of claim 12, wherein the link area is positioned by the encoding link controller according to the block SYNC signal, the EFM SYNC pattern signal, and ~~a~~an EFMCLK pulse signal.

14. ~~The recordable compact disk driver according to~~drive of claim 12, wherein the encoding link controller ~~is to detect the~~detects an area where ~~the a~~ data length is greater than ~~the a~~ maximum run-length of ~~the disk in order to be used~~value to use the area as the linking area.

15. ~~A recordable compact~~An optical disk driver ~~drive~~ having the function of ~~a~~ link writing function, comprising:

~~— an ATIP decoder for providing ATIP time code while reading the data of the disk;~~

an encoding link controller for positioning ~~the a~~ link area ~~of~~ for a succeeding writing and ~~starting~~ generating a succeeding writing signal; and

a ~~micro controller~~ microcontroller for receiving the succeeding writing signal of the encoding link controller and ~~starting~~ initiating a succeeding writing process; and

a laser responsive to the succeeding writing signal, the laser powered in a succeeding writing process to provide laser power to an optical disk at a position corresponding to data written prior to a data writing interruption, thereby providing an overlap area.

16. The recordable compact disk driver according to drive of claim 15, further comprising an ATIP decoder for providing an ATIP time code while reading data from a disk; wherein the link area is positioned by the encoding link controller according to the ATIP time code and the an EFMCLK pulse signal.

17. The drive of claim 15, wherein the overlap layer is set to a length corresponding to a laser power settling time.

18. The method of claim 1, wherein the interrupted and successively written data frame is such that the data frame can be successfully CIRC processed.

19. The method of claim 7, wherein the interrupted and successively written data frame is such that the data frame can be successfully CIRC processed.

20. The drive of claim 12, wherein the laser writes an interrupted data frame portion and a successively written data frame portion that together form an

interrupted and successively written data frame that can be successfully CIRC processed.

21. The drive of claim 15, wherein the laser writes an interrupted data frame portion and a successively written data frame portion that together form an interrupted and successively written data frame that can be successfully CIRC processed.

22. An optical disk drive having a link writing function, comprising:
an encoding link controller for positioning a link area for a succeeding writing and generating a succeeding writing signal; and
a laser responsive to the succeeding writing signal, the laser powered in a succeeding writing process to provide laser power to an optical disk at a successive writing position spaced from an end of data written prior to a data writing interruption by an amount equal to or greater than a maximum run length value of the drive,
the laser writing interrupted data frames and successively written data frames that can together be successfully error-correction processed.

23. A link writing method for a recordable or rewritable optical disk comprising:
determining an interrupted position corresponding to a writing interruption for an optical disk; and

enabling a succeeding writing process after the writing interruption, the succeeding writing process comprising:

searching a linking area by comparing a read data length with a maximum run-length value;

enabling a start writing signal; and

activating a laser power, wherein the linking area is linked to the interrupted position so that interrupted data frames and successively written data frames together form interrupted and successively written data frames that can be successfully error-correction processed.

24. The method of claim 23, wherein the searching the linking area comprises:

setting values of a starting block, a starting data frame, a starting bit count of a writing starting area according to the values of the interrupted sector, the interrupted data frame, the interrupted bit count of the interrupted area, and the maximum run-length value; and

detecting where the read data length is greater than the maximum run-length value and setting the linking area in response thereto.

25. The method of claim 24, further comprising storing values of an interrupted sector, an interrupted data frame, and an interrupted bit count when the writing interruption occurs.

26. The method of claim 25, wherein the writing starting area is set according to the interrupted position and the maximum run-length value so as to maintain the data frame with a same length.

27. The method of claim 25, further comprising writing a section of low reflectivity pattern data following the interrupted position, wherein a length of the low reflectivity pattern data is greater than the maximum run-length value.

28. The method of claim 25, further comprising writing a section of high reflectivity pattern data following the interrupted position, wherein a length of the high reflectivity pattern data is greater than the maximum run-length value.

29. The method of claim 23, wherein the interrupted and successively written data frame is such that the data frame can be successfully CIRC processed.

30. An optical disk drive device having a link writing function, comprising an encoding link controller, responsive to a data writing interruption and a successive determination that data writing can resume, the encoding link controller detecting a pattern from signals read from a disk indicative of the end of a previous interrupted data writing, the pattern characterized by being detectable as being different from normally written data, the encoding link controller generating a start

writing signal in response to detecting the pattern so that the device subsequently initiates a succeeding writing process in response to the start writing signal.

31. The device of claim 30, further comprising a microcontroller coupled to the encoding link controller, the microcontroller initiating the succeeding writing process in response to the start writing signal.

32. The device of claim 30, wherein the device initiates writing the pattern onto the disk after the data writing interruption.

33. The device of claim 32, wherein the pattern consists of high reflectivity pattern data having a length greater than a maximum run length value.

34. The device of claim 33, wherein the disk is rewritable.

35. The device of claim 32, wherein the pattern consists of low reflectivity pattern data having a length greater than a maximum run length value.

36. The device of claim 35, wherein the disk is rewritable.

ABSTRACT

~~The invention provides a~~ A link writing method for a recordable or rewritable compact disk (CD-R) and a driver for using the method. The link writing method includes the steps of "recording a writing interruption address", and "enabling a succeeding writing process" when the causes resulting in after the writing interruption is eliminated. The step of "enabling Enabling a succeeding writing process" includes the steps of "searching the linking area" and "enabling a start writing signal and activating a laser power". The purpose of the invention is to method can accurately link the a succeeding writing area with the a previously written interrupted area with sufficient accuracy to keep the length of allow the data frame consistent without causing errors on data reading to be successfully processed by error correction within the host drive. The linking area is may be positioned either by counting the values of the interrupted block, the interrupted data frame, and the interrupted bit count or by detecting a blank area. Other techniques for positioning the linking area include detecting an unwritten area having a length greater than a maximum or writing a characteristic pattern after an interruption. Due to that the data frame length is kept constant, such as 588T, during linking area, this can be treated as non-interrupted recording area and will not appear decoding error during reading cycle.